

Application of New Pile Driving Formulas

- 1) Cho, Chun-Whan
- 2) Lee, Myung-Whan

Abstract

Although pile driving formulas(or dynamic pile formulas) are regarded as the most practical tool for pile quality control by most engineers, the reliability has long been questioned due to the inherent problems. In reality the dynamic formulas are fundamentally incorrect in terms of the pile driving process. Nevertheless much research on the application of dynamic formula has been carried out regardless of the problems. In this study the problems of the dynamic formula were analysed and new dynamic formula was suggested on the basis of analysis of the problems. The new dynamic formula was appraised using the capacities which were measured at the end of initial driving of piles as well as at the time of restriking by Pile Driving Analyzer. It was found out that the new dynamic formula can be used for the practical tool of pile quality control purpose.

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Key words : Dynamic pile formula, Pile driving formula, Set-up effect, Damping coefficient, PDA

1) 정회원, 삼성물산

2) 정회원, , 대표

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 (1992) 가 .
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 ,
 set-up (relaxation)가
 가 가
 가 ,
 . Cheng
 (1996), Paikowsky (1996), (1997)
 가 .

2.

1893 Wellington (Engineering News Formula)

(Poulos, 1980) (1)

$$R_u = \frac{e_h \cdot W_r \cdot H}{S + (C \cdot R_u \cdot L) / (2AE_p) + \Delta S_{pp}} \cdot \frac{W_r + n^2 W_p}{W_r + W_p} \dots\dots (1)$$

, R_u : , e_h : , W_r : , H : , S : ,
 C : , L : , A : , E_p : , ΔS_{pp} :

, W_p : () n:

(1) 가 Newton

450

(US DOT, 1984).

, Hiley , Danish , Gate , Janbu

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o

가

o

가

(high shear rate)

o

가

o

가

가

Peck(1941), Agerschou (1962), Olson

(1967), Tavenas (1972), Teichman (1984), (1987), Broms (1988), (1992),

Paikowsky (1992, 1966), Cheng (1996) (1997)

(pile driving analyzer, PDA)

가

Peck(1941), Tavenas (1972)

, Tavenas (1972)

. Broms (1988), Cheng (1996)

Hiley

±25.0%

Paikowsky(1992, 1996)

(K_{sp} ,
/) , 가 . Paikowsky
,
가
가 .

FHWA (US DOT, 1996)

WEAP(wave equation analysis of driven piles)

가

가

(1997)

PDA

(end of initial driving, E.O.I.D)

(site specific factor of safety)

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가

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가

3.

가

, set-up

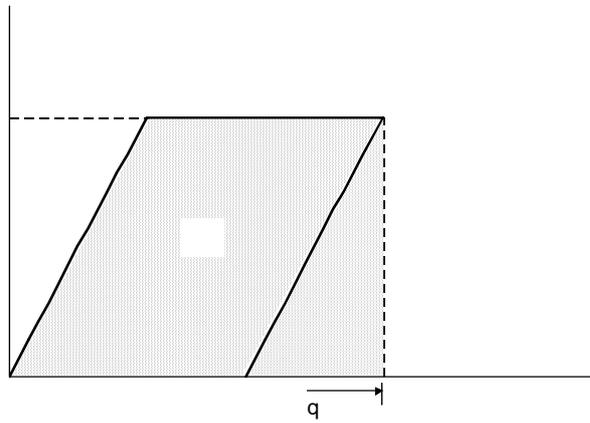
가

Smith(1960)

1 (set value, S) (q)
 (2)

$$W = R_t(S + \frac{q}{2}) \dots\dots\dots (2)$$

, W :
 R_t :
 S :
 q :



1.

(2) (3)

$$R_t = \frac{W}{S + q/2} \dots\dots\dots (3)$$

(EMX), (q) (4)

(5) (PDI, 1995).

$$EMX = E(t)_{max} = \int_0^t V(t) \cdot F(t) \cdot dt \dots\dots\dots (4)$$

$$q = \int_0^t V(t) \cdot dt - S \dots\dots\dots (5)$$

$$= DMX - S$$

, V(t) :

F(t) :

DMX :

(3) (4) (5) (6) .

$$R_t = \frac{EMX}{S + \frac{1}{2}(DMX - S)} \dots\dots\dots (6)$$

(6) R_t (R_d) (R_s)
 가 가

$$R_d = J_v \cdot V_t = J_s \cdot V_t \cdot R_s = J_c \cdot Z \cdot V_t \dots\dots\dots (7)$$

, J_v : Viscous damping (t/m/s)

J_s : Smith damping (s/m)

J_c : Case damping ()

Z : (impedence ; t/m/s)

V_t : (m/s)

Case CAPWAP(CAse Pile Wave Analysis
 Program) Case damping Smith damping ($R_s \approx R_{ul}$ 가정) R_{ul}
 (GRL Inc.,1996).

(R_t) (8) (9) , damping

(R_s) (10) (11) .

$$R_t = R_d + R_s$$

$$R_{ts} = J_s \cdot V_t \cdot R_s + R_s \text{ (Smith damping)} \dots\dots (8)$$

$$R_{tc} = J_c \cdot Z \cdot V_t + R_s \text{ (Case damping)} \dots\dots\dots (9)$$

$$R_s = \frac{R_t}{1 + J_s \cdot V_t} \text{ (Smith damping)} \dots\dots\dots (10)$$

$$= R_t - J_c \cdot Z \cdot V_t \text{ (Case damping)} \dots\dots\dots (11)$$

(10) (11) (R_s)

(R_t) 가 (set-up factor, S_f :

) , (R_{it}) (12) (13) 가

$$R_{it} = R_s \cdot S_f$$

$$= \left(\frac{S_f}{1 + J_s \cdot V_t} \right) \cdot \frac{EMX}{S + \frac{1}{2}q} \dots\dots\dots (12)$$

$$= S_f \left(\frac{EMX}{S + \frac{1}{2}q} - J_c \cdot Z \cdot V_t \right) \dots\dots\dots (13)$$

(12) (13) 가

가 가 S q

가 가 , S

가 .

damping (J_c, J_s) 가

(PDI, 1995) 가 .

가 가

가 가 ,

damping 가 damping 가

가 .

damping 가 (6)

$$S_a = \frac{\sum \left(\frac{R_{u_i}}{R_{t_i}} \right)}{m} \dots\dots\dots (14)$$

, S_a :

R_{t_i} : ((6))

R_{u_i} :

m :

(14)

(S, q)

$$R_u = S_a \cdot R_t$$

$$= S_a \cdot \frac{EMX}{S + \frac{1}{2}q} \dots\dots\dots (15)$$

$$R_{tt} = R_u \cdot S_f$$

$$= S_f \cdot S_a \cdot \frac{EMX}{S + \frac{1}{2}q} \dots\dots\dots (16)$$

(12), (13), (16) S_a S_f

, EMX

, S q

가

가

4.

3

가

가

6

4

1

(1998)

2

1.

Case damping , (13)	$R_{tt} = S_f \left(\frac{EMX}{S + \frac{1}{2}q} - J_c \cdot Z \cdot V_t \right)$	S_f : (CAPWAP) EMX : (CAPWAP)
Smith damping , (12)	$R_{tt} = \left(\frac{S_f}{1 + J_s \cdot V_t} \right) \cdot \frac{EMX}{S + \frac{1}{2}q}$	J_c, J_s : (CAPWAP) V_t : (CAPWAP)
, (16)	$R_{tt} = S_f \cdot S_a \cdot \frac{EMX}{S + \frac{1}{2}q}$	S : () q : () S_a : (CAPWAP)
	S_f : 가 S_a : EMX : (t·cm) S : (cm) q : (cm)	J_c : Case damping (RSP RMX) J_s : Smith damping (cm/s) V_t : (cm/s) Z : (t/cm/s)

2.

			(ton)		(ton)			(ton)				
					Smith	Case		Smith	Case			
1	406×7.9 t	DKH5	189.0	243.0	164.5	159.2	215.1	211.5	204.7	276.6	S	SG
2	406×7.9 t	DKH7	155.0	244.0	138.0	202.0	144.4	217.2	318.0	227.2	SG	SG
3	406×7.9 t	DKH7	172.0	222.0	136.2	205.4	154.6	175.8	265.1	199.6	S	S
4	406×7.9 t	DKH7	206.0	242.0	216.0	209.9	210.7	253.7	246.6	247.5	S	S
5	508×9.5 t	DKH7	310.0	370.0	290.9	300.3	281.1	347.2	358.4	335.5	SM	SM
6	508×9.5 t	DKH7	317.0	381.0	272.2	349.6	329.1	327.2	420.2	395.5	SM	SM
7	406×9.5 t	DKH7	241.5	311.4	218.9	258.1	240.3	282.3	332.8	309.9	SM	SM
8	406×9.5 t	DKH7	296.0	351.7	262.2	313.0	310.9	311.5	371.9	369.4	SM	SM
9	508×9.3 t	DKH7	328.0	363.6	288.9	325.5	363.6	320.3	360.8	403.1	SM	SM
10	406×9.3 t	DKH7	351.0	NA	267.7	354.2	340.2	NA	NA	NA	SM	SM
11	323×9.3 t	DKH7	284.0	278.0	227.9	295.5	281.4	223.1	289.3	275.4	SM	SM
12	273×9.1 t	DKH7	255.0	247.0	193.1	257.0	233.6	187.0	248.9	226.3	SM	SM
13	406×10 t	DKH7	211.0	300.0	148.6	234.0	224.2	211.3	332.7	318.7	S	S
14	406×10 t	DKH7	249.0	300.5	186.8	260.6	215.8	225.4	314.5	260.4	S	S
15	406×10 t	DKH7	270.0	312.1	233.7	282.9	266.3	270.1	327.0	307.8	S	S
16	406×10 t	DKH7	285.0	315.8	234.2	275.9	307.1	259.5	305.7	340.3	S	S
17	PHC 400	DKH7	185.0	235.9	148.5	204.3	202.1	189.4	260.5	257.7	S	S
18	PHC 400	DKH7	240.0	297.6	186.0	300.0	225.6	230.6	372.0	279.7	S	S
19	PHC 400	DKH7	249.2	295.0	236.0	283.8	246.6	279.4	336.0	291.9	S	S
20	PHC 400	DKH7	252.7	276.3	139.8	324.3	243.8	152.9	354.6	266.6	S	S
21	609×12 t	DKH10	392.0	624.4	277.5	379.4	423.5	442.0	604.3	674.5	C	S
22	406×12 t	DKH7	250.8	268.7	159.6	299.0	208.0	171.0	320.3	222.8	SM	SG
23	406×12 t	DKH7	282.6	332.2	288.7	309.0	278.6	339.4	363.2	327.5	C	S
24	609×12 t	DKH10	340.0	431.1	232.5	327.6	379.9	294.8	415.4	481.7	SM	S
25	PHC 350	JTN5	80.0	190.9	51.6	58.4	77.5	123.1	139.4	185.0	S	SG
26	PHC 350	NH40	86.4	113.0	48.8	103.7	89.4	63.8	135.6	117.0	S	SG
27	PHC 350	NH40	81.3	145.4	75.3	65.6	71.5	134.7	117.3	127.9	S	SG
28	PHC 350	NH40	67.7	99.0	38.6	60.7	75.7	56.4	88.8	110.7	S	SG
29	PHC 450	NH70	53.9	225.9	38.6	71.6	67.7	161.8	300.1	283.6	C	C
30	PHC 450	NH70	71.8	201.0	38.5	59.4	73.0	107.8	166.3	204.4	C	C
31	PHC 450	NH70	172.0	234.7	148.1	143.5	164.4	202.1	195.8	224.4	C	C
32	PHC 450	DKH7	197.1	270.8	171.0	200.0	150.4	234.9	274.8	206.6	C	C

) 1. (E.O.I.D) (Restrike)

가

2. NA

3. S, C, SG, SM

2

가 Case

damping

Smith damping

Smith damping

가

CAPWAP

R_s

R_{ul}

(7)

(R_s)

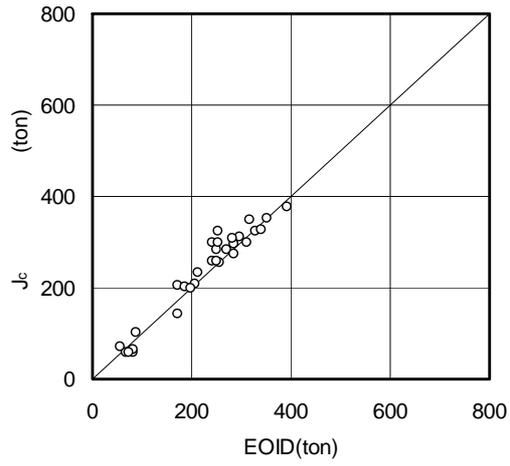
(V)

R_s

3

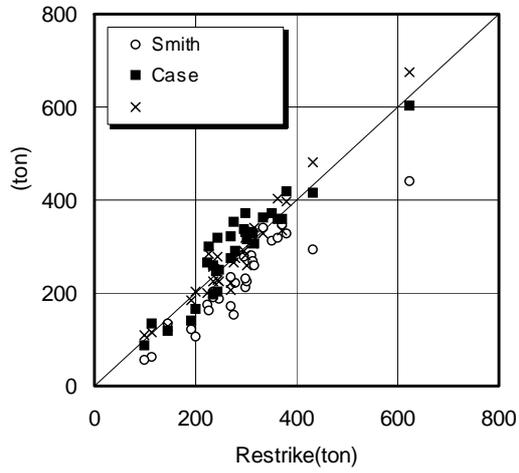
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(12), (13), (16)

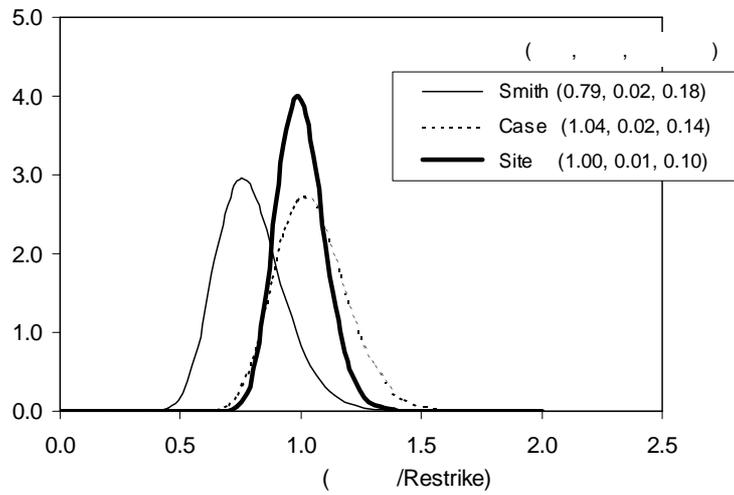


(b) Case damping ((11))

2.



3.



4.

5.

“Peck(1942)

가

가

, set-up

Terzaghi(1943)

가

가가

damping

, set-up

가

Smith damping

Case damping

가

가

set-up

가

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2. (1998), “ ”, , , pp.198
3. , , , (1997), “ ”, '97 , , pp.55 62.
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